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|---|---|--------|----|--|--------|---|
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| | | | _ | | _ | |

| | Educational, Academic, R&D | Industrial | |
|----------------------|----------------------------|-----------------|--|
| Weight [kg] | | | |
| | 0.78 | 0.99 | |
| Max payload [kg] | | | |
| pinch grasp | 0.83 | 0.6 | |
| power grasp | 1.7 | 2.0 | |
| Voltage [VDC] | | | |
| | 12, 24 | 24 | |
| Colour | | | |
| | | | |
| Glove | | | |
| | integrated | interchangeable | |
| Dimensions [mm] | | | |
| width | 191 | 185 | |
| length | 250 | 244 | |
| thickness | 71 | 83 | |
| Flange interface | | | |
| ISO 9409-1-31.5-4-M5 | + | + | |
| ISO 9409-1-40-4-M6 | + | + | |
| ISO 9409-1-50-4-M6 | ✓ | \checkmark | |
| Wrist | | | |

Communication protocol

| | RS-485 | EtherCAT, UDP, Digital I/Os |
|--------------------------|--------------|---|
| Software | | |
| ₩ROS | ✓ | + |
| MATLAB SIMULINK | \checkmark | + |
| C/C++ API | \checkmark | \checkmark |
| UR+ | \checkmark | \checkmark |
| Franka App | + | + |
| Electronic Driver | | |
| | Embedded | External |
| IP Code | | |
| | _ | IP65 |
| Normative compliance | | |
| ✓ available + on request | _ | ISO 12100, ISO/TS 15066, ISO 13849-1/-2, ISO 10210-1/-2, ISO 9409-1-50-4-M6, ISO/TR 20218-1, IEC 60529, IEC 61000-6-2/-6-4 |